

1 Section 1.1

Consider the system (of linear equations)

$$\begin{array}{rrrrr} x_1 & -2x_2 & -x_3 & +3x_4 & = 1 \\ 2x_1 & -4x_2 & +x_3 & & = 5 \\ x_1 & -2x_2 & +2x_3 & -3x_4 & = 4 \end{array} \quad (1.1)$$

2 Sec 1.3 Vector equations

Write an vector equation that is equivalent to the system (1.1)

3 Sec 1.4 The matrix equation $Ax = b$

Write a matrix equation that is equivalent to the system (1.1)

Let $A = \begin{bmatrix} 1 & -2 & -1 & 3 \\ 2 & -4 & 1 & 0 \\ 1 & -2 & 2 & -3 \end{bmatrix}$.

4 Sec 1.1 Systems of linear equations and Sec 1.2 Row reduction and echelon forms

Is the system from (1.1), $\begin{cases} x_1 & -2x_2 & -x_3 & +3x_4 & = 1 \\ 2x_1 & -4x_2 & +x_3 & & = 5 \\ x_1 & -2x_2 & +2x_3 & -3x_4 & = 4 \end{cases}$ consistent or inconsistent?

Fact: A system of linear equations has ...

1. no solutions, or
- 2.
- 3.

(Con't answering Question 4)

The augmented matrix of the system (1.1) is

$$\left[\begin{array}{cccc|c} 1 & -2 & -1 & 3 & 1 \\ 2 & -4 & 1 & 0 & 5 \\ 1 & -2 & 2 & -3 & 4 \end{array} \right] \quad (4.1)$$

Row reduce:

An echelon form of the augmented matrix (4.1) gives us enough information to determine whether a system is consistent/inconsistent because of the following theorem.

Theorem:

A linear system is _____ if and only if

Since an echelon form of the augmented matrix (4.1) _____, the system (1.1) is _____.

Optional: Continue to row reduce to obtain the UNIQUE _____:

$$\left[\begin{array}{cccc|c} 1 & -2 & 0 & 1 & 2 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

5 Sec 1.3 and 1.4

Is $\begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix}$ in the subset of $\mathbb{R}^3$ spanned by the columns of $A = \begin{bmatrix} 1 & -2 & -1 & 3 \\ 2 & -4 & 1 & 0 \\ 1 & -2 & 2 & -3 \end{bmatrix}$? Why/why not?

Let $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -2 \\ -4 \\ -2 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}$, and $\mathbf{v}_4 = \begin{bmatrix} 3 \\ 0 \\ -3 \end{bmatrix}$.

The subset of $\mathbb{R}^3$ spanned (or generated) by $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$, denoted

_____,

is ...

6 Sec 1.5 Solution sets of linear systems

(a) Describe all solutions of the _____ system

$$\begin{bmatrix} 1 & -2 & -1 & 3 \\ 2 & -4 & 1 & 0 \\ 1 & -2 & 2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ 4 \end{bmatrix}$$

$$\left[\begin{array}{cccc|c} 1 & -2 & -1 & 3 & 1 \\ 2 & -4 & 1 & 0 & 5 \\ 1 & -2 & 2 & -3 & 4 \end{array} \right] \longrightarrow \left[\begin{array}{cccc|c} 1 & -2 & 0 & 1 & 2 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

The variables that don't correspond to the pivot columns, x_2 and x_4 , are called _____.

The solutions are ...

(b) Describe all solutions of the _____ system

$$\begin{bmatrix} 1 & -2 & -1 & 3 \\ 2 & -4 & 1 & 0 \\ 1 & -2 & 2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{cccc|c} 1 & -2 & -1 & 3 & 1 \\ 2 & -4 & 1 & 0 & 5 \\ 1 & -2 & 2 & -3 & 4 \end{array} \right] \longrightarrow \left[\begin{array}{cccc|c} 1 & -2 & 0 & 1 & 2 \\ 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

The solutions are ...

(c) Does $A\mathbf{x} = \mathbf{0}$ have a nontrivial solution?

Fact:

(a) A homogeneous linear system has at least one solution $\mathbf{x}=\mathbf{0}$, called the _____.

(b) A _____ is a _____ satisfying $A\mathbf{x} = \mathbf{0}$.

7 Sec 1.7 Linear independence

Let $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} -2 \\ -4 \\ -2 \end{bmatrix}$, $\mathbf{v}_3 = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}$, and $\mathbf{v}_4 = \begin{bmatrix} 3 \\ 0 \\ -3 \end{bmatrix}$.

(a) Determine (using work we've already done) whether the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ is linearly dependent.

Fact:

The columns of a matrix M are linearly independent if and only if the matrix equation $M\mathbf{x} = \mathbf{0}$ has _____.

(b) Determine by inspection whether the set $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4\}$ is linearly dependent.

8 Sec 1.8 Intro to linear transformations

- A matrix transformation T is a function (or mapping or map)

$$T : \mathbb{R}^n \rightarrow \mathbb{R}^m \quad \text{defined by} \quad T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n$$

where A is an _____

- _____ is the set of all images $T(\mathbf{x})$.
- Note: Each image $T(\mathbf{x})$ is of the form $A\mathbf{x}$, ie.

Example: Define a mapping $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = \begin{bmatrix} 1 & -3 \\ 3 & 5 \\ -1 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 3x_2 \\ 3x_1 + 5x_2 \\ -x_1 + 7x_2 \end{bmatrix} \quad \text{or} \quad x_1 \begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix} + x_2 \begin{bmatrix} -3 \\ 5 \\ 7 \end{bmatrix}$$

- (a) Find the image $T(\mathbf{u})$ of $\mathbf{u} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ under the mapping T .

- (b) Is $\mathbf{b} = \begin{bmatrix} 3 \\ 2 \\ -5 \end{bmatrix}$ in the range of T ? Is $\mathbf{c} = \begin{bmatrix} 3 \\ 2 \\ 5 \end{bmatrix}$ in the range of T ?

Linear transformations

Def: Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a function.

(i) T preserves _____

if: $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ for all $\mathbf{u}, \mathbf{v}$ in the domain of T .

(ii) T preserves _____

if: $T(c\mathbf{u}) = cT(\mathbf{u})$ for all scalars c in $\mathbb{R}$ and all $\mathbf{u}$ in the domain of T .

The function T is called _____

if:

Sec 1.8 Exercise 41

Show that the function $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by

$$T \left(\begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} 2x - 3y \\ x + 4 \\ 5y \end{bmatrix}$$

is linear or not linear.