The Box-Ball System: Soliton Decomposition and Robinson-Schensted algorithm (University of Connecticut Math REU 2020)

2020 MRC workshop: Combinatorial Applications of Computational Geometry and Algebraic Topology

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Motivation: Soliton waves

- ► At time -∞, soliton waves are traveling through space at different speeds, not minding each other.
- At some time, they begin to collide with one another, causing interference, and for a while you have a mess.
- But eventually by time $+\infty$ the interference sorts itself out, and the solitons continue on their way as if it hadn't happened.

t

Start with an initial configuration $\pi = \pi_1 \pi_2 \pi_3 \dots \pi_k$, where π is a permutation.

Step 1: Write the permutation on a strip of infinite boxes:

$$t = 0$$
 4 5 2 3 6 1 . . .

Step 2: To complete a box-ball move, let each number (or "ball") jump to the next available spot (or "box") to the right. First move 1, then move 2, and so on.

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Step 3: Continue moving numbers from smallest to largest to their nearest available spots until every number in the permutation has been moved.



We are now at the t = 1 state and we have completed one BBS move.



Continue making BBS moves.

(Here, 4 moves are shown).



Note. (Backwards BBS)

▶ Move balls from **largest-to-smallest** to their nearest available spaces to the **left**.

▶ The time-values after each backwards box-ball move now decrease.

Box-Ball System: Soliton Decomposition

At a certain point, the system reaches a *steady state* where:

- blocks of increasing sequences (or *solitons*) move together at a speed equal to their length.
- ▶ the sizes of the solitons are weakly increasing from left to right
- ▶ order of the solitons remain unchanged



Step 5: After reaching steady state, create a soliton decomposition diagram $SD(\pi)$ by stacking solitons from right to left.

$$t=4$$
 4 2 5 1 3 6 \cdots

The shape of the diagram always forms a partition (weakly decreasing sequence of positive integers):

Soliton decomposition
$$SD(\pi) = \begin{bmatrix} 1 & 3 & 6 \\ 2 & 5 \\ 4 \end{bmatrix}$$
 with shape $(3, 2, 1)$.

REU Questions.

When does a permutation reach its steady-state? How many permutations in S_n first reach its steady-state at a given time t?

Tableaux

Definition. (Young Tableaux)

- ▶ A *tableau* is an arrangement of numbers $\{1, 2, ..., n\}$ in Young diagram (sequence of weakly decreasing rows).
- ▶ A tableau is *standard* if the rows and columns are increasing sequences.
- ▶ The *reading word* of a standard Young tableau is the permutation formed by concatenating the rows of the tableau from bottom to top.

Example. (Standard Young Tableau)

- $\frac{12}{34}$ is a standard tableau. Its reading word is 53412.
- $\blacktriangleright \frac{\frac{1}{2}}{\frac{5}{2}}$ is a nonstandard tableau.

REU Question.

When is a soliton decomposition standard?

Robinson-Schensted insertion algorithm

$$\pi = 452361 \longrightarrow \begin{bmatrix} 1 & 3 & 6 \\ 2 & 5 \\ 4 \end{bmatrix} = P$$

- ▶ The *Robinson-Schensted (RS) insertion algorithm* is a famous bijection from permutations to pairs of standard tableaux.
- Given a permutation $\pi = \pi_1 \cdots \pi_n$, the first tableau in the pair, denoted $P(\pi)$, is called the insertion tableau or *P*-tableau of π .

REU Question.

For what permutations π do we have $SD(\pi) = P(\pi)$?

Soliton decomposition vs P-tableau

Theorem

The following are equivalent:

- 1. $SD(\pi) = P(\pi)$.
- 2. $SD(\pi)$ is a standard tableau.

Conjecture

The following is equivalent to (1) and (2).

3. $\operatorname{sh} \operatorname{SD}(\pi) = \operatorname{sh} \operatorname{P}(\pi)$.

Knuth Relations

Definition

Suppose π , $\sigma \in S_n$ and x < y < z.

▶ π and σ differ by a Knuth relation of the **first kind** (K₁) if

 $\pi = x_1 \dots y \mathbf{x} z \dots x_n$ and $\sigma = x_1 \dots y z \mathbf{x} \dots x_n$

▶ π and σ differ by a Knuth relation of the second kind (K₂) if

 $\pi = x_1 \dots x_2 y \dots x_n$ and $\sigma = x_1 \dots z x y \dots x_n$

▶ π and σ differ by Knuth relations of **both kinds** (K_B) if

 $\pi = x_1 \dots y_1 x z y_2 \dots x_n \text{ and } \sigma = x_1 \dots y_1 z x y_2 \dots x_n$ for $x < y_1, y_2 < z$

Soliton Decomposition and Knuth moves

• Let r denote the reading word of $P(\pi)$. The RSK theory tells us there is a path of Knuth moves from π to r.

Theorems

- If there exists a path from π to r such that no move along the path is K_B , then $\operatorname{sh} \operatorname{SD}(\pi) = \operatorname{sh} P(\pi)$.
- If there exists a path from π to r containing an odd number of K_B moves, then $SD(\pi) \neq P(\pi)$.

Results Involving Steady-State Times

Let $a_{n,t}$ be the number of permutations in S_n which first reach their soliton decompositions at time t. Let $F_n(x) = a_{n,0} + a_{n,1}x + a_{n,2}x^2 + a_{n,3}x^3 + \ldots$ be the generating function of the sequence $\{a_{t,n}\}_{t>0}$.

Theorem: classification of permutations with steady-state value of t = 0

- A permutation r reaches its soliton decomposition at t = 0 if and only if r is the reading word of a standard tableau.
- ▶ In particular, the constant value of $F_n(x)$ is the number of standard tableaux with *n* boxes.

Theorem: a class of permutations with steady-state value of t = 1

If a permutation π is related to a reading word of a standard tableau by one K_1 or K_1 move (but not K_B), then π first reaches its soliton decomposition at t = 1.

n-3 conjecture

The generating function $F_n(x)$ is a polynomial of degree at most n-3.

Insertion algorithm for soliton decomposition

"Carrier" Algorithm

• Given a BBS state at time t, compute the state at time t + 1

Theorem: "M-carrier" algorithm and insertion algorithm

• Given a BBS state at time t, compute the state at time t + M

Work in progress: RSK-like insertion algorithm for soliton decomposition

- ▶ Define an "unlimited-carrier" algorithm
- Compute the soliton decomposition using insertion/bumping similar to Robinson-Schensted (RS) insertion algorithm.
- When $SD(\pi) = P(\pi)$, the "unlimited-carrier" algorithm is equivalent to the usual RS insertion algorithm

Thank You!