# Chaos: The Predictably Unpredictable 

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## Outline

# Part 1: An Introduction to Dynamical Systems 

Part 2: What is Chaos?

Part 3: Examples of Chaotic Dynamics

## Dynamical Systems

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■ Differential Equations: Useful for quantities that evolve continuously over time.

- Difference Equations: Useful for quantities with generational dependence (discrete steps with finite size)


## Differential Equations (DE)

■ Applications: Physics, Engineering, Economics, etc

- Solve the Initial Value Problem (IVP):

$$
\frac{d y}{d x}=\frac{1}{2 \sqrt{x}}, \quad y(1)=1
$$

- The solution is a function $y(x)$ satisfying $\frac{d y}{d x}=\frac{1}{2 \sqrt{x}}$ and $y(1)=1$


## Numerical Approximations

- Most DE's cannot be solved so cleanly
- Consider the general DE:

$$
\frac{d y}{d x}=f(x, y), \quad y\left(x_{0}\right)=y_{0}
$$

- Numerical Approximations with Euler's Method


## Numerical Approximations



## Difference Equations ( $\Delta \mathrm{E}$ )

- Applications: Biology, entomology, epidemiology, economics, chaos, etc.

- Can be derived from DE's
- $\Delta \mathrm{E}$ 's are recurrence relations

■ A solution to a $\Delta E$ is a sequence of points

## The Fibonacci Sequence



## 1st Order Difference Equations

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\begin{equation*}
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■ Global Dynamics: Determine behavior of $\gamma^{+}\left(x_{0}\right)$ for any choice of $x_{0}$.

## Systems of Difference Equations

- 2D System of Difference Equations:

$$
\begin{aligned}
& x_{n+1}=f\left(x_{n}, y_{n}\right), n=1,2, \ldots \\
& y_{n+1}=g\left(x_{n}, y_{n}\right)
\end{aligned}
$$

■ Associated Map: $T: \mathcal{R} \rightarrow \mathcal{R}, T(x, y)=(f(x, y), g(x, y))$

- Positive Orbit: For $\left(x_{0}, y_{0}\right) \in \mathbb{R}^{2}$ the positive orbit is

$$
\gamma^{+}\left(x_{0}, y_{0}\right)=\left\{\left(x_{0}, y_{0}\right), T\left(x_{0}, y_{0}\right), T^{2}\left(x_{0}, y_{0}\right), \ldots\right\}
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■ Global Dynamics: Determine behavior of $\gamma^{+}\left(x_{0}, y_{0}\right)$ for any choice of $\left(x_{0}, y_{0}\right)$.

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- Deterministic: The output/ behavior of solutions to a model are fully determined by the parameters and the set of initial conditions.
- Stochastic: (AKA Probabilistic) There is a probability associated with different outputs/ behaviors so the same set of parameters and initial conditions can lead to a bevy of different outputs.


## Determinism: Laplace's Superman

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We may regard the present state of the universe as the effect of its past and the cause of its future. An intellect which at a certain moment would know all forces that set nature in motion, and all positions of all items of which nature is composed, if this intellect were also vast enough to submit these data to analysis, it would embrace in a single formula the movements of the greatest bodies of the universe and those of the tiniest atom; for such an intellect nothing would be uncertain and the future just like the past would be present before its eyes.

## The Art of Prediction

The ideal situation:
1 Same causes always produce the same effects.
2 Like causes always produce like effects.


The game of Pool

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A small change to one state of a deterministic dynamical system can result in large differences in a later state.

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Let's see some examples!

## EX 1: The Double Pendulum [Setup]



## Double Pendulum

- Two masses $m_{1}, m_{2}$
- Two lengths $L_{1}, L_{2}$
- Two pivot points and corresponding angles $\theta_{1}(t)$ and $\theta_{2}(t)$
- GOAL: Track $m_{2}$ (i.e. the far tip) by tracking $\theta_{1}(t)$ and $\theta_{2}(t)$


## The Double Pendulum: System of DE's

$$
\begin{gathered}
\theta_{1}^{\prime \prime}=\frac{-g\left(2 m_{1}+m_{2}\right) \sin \theta_{1}-m_{2} g \sin \left(\theta_{1}-2 \theta_{2}\right)-2 \sin \left(\theta_{1}-\theta_{2}\right) m_{2}\left(\theta_{2}^{\prime 2} L_{2}+\theta_{1}^{\prime 2} L_{1} \cos \left(\theta_{1}-\theta_{2}\right)\right)}{L_{1}\left(2 m_{1}+m_{2}-m_{2} \cos \left(2 \theta_{1}-2 \theta_{2}\right)\right)} \\
\theta_{2}^{\prime \prime}=\frac{2 \sin \left(\theta_{1}-\theta_{2}\right)\left(\theta_{1}^{\prime 2} L_{1}\left(m_{1}+m_{2}\right)+g\left(m_{1}+m_{2}\right) \cos \theta_{1}+\theta_{2}^{\prime 2} L_{2} m_{2} \cos \left(\theta_{1}-\theta_{2}\right)\right)}{L_{2}\left(2 m_{1}+m_{2}-m_{2} \cos \left(2 \theta_{1}-2 \theta_{2}\right)\right)}
\end{gathered}
$$

# The Double Pendulum: Simulation 

Double Pendulum Simulation

Double Pendulum, Side-by-side

Triple Pendulum Simulation

## EX 2: The Gingerbread Man

## 2D System of $\Delta E$ 's

$$
\begin{aligned}
& x_{n+1}=1-y_{n}+\left|x_{n}\right| \\
& y_{n+1}=x_{n},
\end{aligned} \quad n=1,2, \ldots
$$

Let's check out the dynamics for some different choices of $x_{0}, y_{0}$.


EX 3: The Lorenz Attractor


## EX 3: The Lorenz Attractor

- Meteorologist Edward Lorenz, 1963 (MIT)
■ Model convection in atmosphere
- 3D System of Differential Equations. Variables $(x, y, z)$
■ Simulated with computer to track solutions (i.e how atmosphere changes)


## EX 3: The Lorenz Attractor

$$
\begin{aligned}
& \dot{x}=\sigma(y-x) \\
& \dot{y}=x(\rho-z)-y \\
& \dot{z}=x y-\beta z
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$\square x, y$, and $z$ represent states of atmosphere (temperature, wind speed, humidity, pressure, etc.)
■ $\alpha, \rho, \beta$ represent certain fixed physical properties of the atmosphere
■ After Lorenz ran a simulation, he went for coffee break, came back and...

## EX 3: The Lorenz Attractor

Lorenz Demo


## EX 4: Fun w/ Periodic Points

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& x_{n+1}=\frac{1+x_{n}}{x_{n-1}}, \quad n=0,1,2, \ldots
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- $x_{n+1}=\frac{x_{n}}{x_{n-1}}, \quad n=0,1,2, \ldots \quad$ All positive orbits are Period 6


## EX 5: The Logistic Map

- Logistic $\Delta \mathrm{E}$ :

$$
x_{n+1}=r x_{n}\left(1-x_{n}\right), \quad x_{0} \in[0,1], r \in(0,4]
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- Sensitive dependence on initial conditions

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That's All Folks


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