Lecture 18

Linear transformations (revisited)



Definition: A linear transformation (between vector spaces)

Let V and W be vector spaces. A function $T: V \rightarrow W$ is a **linear** transformation if

• T preserves addition. If v and w are in V, then

$$T(v+w) = T(v) + T(w)$$

• T preserves scalar multiplication. If v is in V and c is in \mathbb{R} , T(cv) = cT(v)

They are also called linear operators, linear maps, or linear functions.

If f(x) and g(x) are smooth functions with

$$f'(x) = \sin(x)$$
 and $g'(x) = e^x$

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then the linearity of the derivative operator tells us that $\frac{d}{dx}(2f(x) - 4g(x)) = 2\sin(x) - 4e^{x}$

Examples of linear transformations

• Many geometric transformations.

Reflection, rotation, projection, etc.

• Many differential operators; e.g.

 $H: \mathcal{C}^{\infty} \to \mathcal{C}^{\infty} \qquad H(f):=f''+f$

 The shift operator on sequences S : S → S which deletes the first term and shifts everything else over.

$$S(x_0, x_1, x_2, x_3, ...) := (x_1, x_2, x_3, x_4, ...)$$

• Sending a matrix to its transpose defines a linear map

$$\top : \mathbb{R}^{m \times n} \to \mathbb{R}^{n \times m}$$

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• Sums, scalar multiples, and compositions of linear transformations are still linear.

The map which sends a 2×2 matrix to its determinant is not a linear transformation. Why?

We can use linear transformations to generalize matrix concepts.

Images and kernels of a linear transformation

Let $T: V \to W$ be a linear transformation.

• The kernel of T is the subspace of V defined by

 $\ker(T) := \{v \mid v \text{ in } V \text{ such that } T(v) = 0\}$

• The **image** of *T* is the subspace of *W* defined by

 $\operatorname{im}(T) := \{T(v) \mid v \text{ in } V\}$

Notice that we've snuck in the fact that ker(T) and im(T) are subspaces.

Intuition

- The kernel is the set of inputs sent to the zero element by T.
- The image is the set of actual outputs of *T*.

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Exercise 1(a)

Let $F : \mathbb{P}_3 \to \mathbb{P}_3$ be the linear transformation defined by =

$$F(p(x)) := (x-2)p'(x)$$

- Determine whether $x^2 1$ is in the kernel of *F*.
- **2** Determine whether 16 is in the kernel of F.
- **3** Determine whether $x^2 1$ is in the image of *F*.
- Determine whether $x^2 4$ is in the image of *F*.
- Find the dimension of the kernel of F. Write down a basis for the kernel of F.

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One of our favorite theorems generalizes.

The Rank-Nullity Theorem (for linear transformations) If $T: V \to W$ is a linear transformation, then $\dim(\operatorname{im}(T)) + \dim(\ker(T)) = \dim(V)$

This can be interpreted with the following intuitive picture.

$$\underbrace{(\text{starting dim})}_{\dim(V)} - \underbrace{(\text{dim destroyed by } T)}_{\dim(\ker(T))} = \underbrace{(\text{dim after applying } T)}_{\dim(\operatorname{im}(T))}$$

Exercise 1(b)

• What is dim(im(F)) from the previous exercise? <u>Solution</u>: Because dim $(\mathbb{P}_3) = 4$ and we computed dim(ker(F)) = 1, we know that

$$\dim(\operatorname{im}(F)) = 4 - 1 = 3$$

2 Write down a basis for im(F).

Exercise 2

Suppose $\mathcal{T}:\mathbb{P}_4\to\mathbb{P}_6$ is a linear transformation given by

T(v) = 0 for all v in \mathbb{P}_4 .

What is the dimension of the kernel of T?

Recall that \mathbb{P}_4 has dimension 5, and \mathbb{P}_6 has dimension 7.

Possible solution A

Since T(v) = 0 for all v in \mathbb{P}_4 , we have $im(T) = \{0\}$. So dim(im(T)) = 0. The theorem tells us

 $\dim(\operatorname{im}(T)) + \dim(\ker(T)) = \dim(\operatorname{domain} \text{ of } T),$

so
$$\dim(\operatorname{im}(T)) + \dim(\ker(T)) = \dim(\mathbb{P}_4)$$

 $0 + \dim(\ker(T)) = 5$

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Exercise 2

Suppose $T : \mathbb{P}_4 \to \mathbb{P}_6$ is a linear transformation given by

T(v) = 0 for all v in \mathbb{P}_4 .

What is the dimension of the kernel of T?

Possible solution B

Since T(v) = 0 for all v in \mathbb{P}_4 , the kernel of T is the entire \mathbb{P}_4 . So ker $(T) = \mathbb{P}_4$. So dim $(ker(T)) = dim(\mathbb{P}_4) = 5$.

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