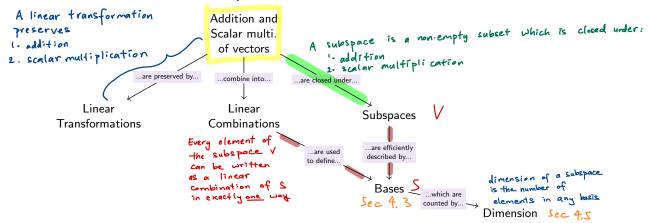
## Sec 4.1 Vector spaces and subspaces

 Observation 1: Many linear algebra concepts can be defined in terms of addition and scalar multiplication



Observation 2: Addition and scalar multiplication make sense for many other mathematical objects.

Examples

Polynomials

 $(1+x^2)+(7-3x+x^3)$ 

Real-valued functions of x  $\sin(x) + e^x$ 

Scalar multiplication  $4(1+3x+4x^2)$ 

4 ln(x)

Vector space

**Goals:** Generalize what we've learned so far about vectors to other kinds of objects we can add and scalar multiply.

#### Definition: A vector space

A **vector space** is a set V in which

- ullet there is a rule to add any two elements v,w in V, and
- there is a rule to multiply any v in V by any scalar r in  $\mathbb{R}$ ,

such that the axioms on the next slide hold.

Intuitively, a vector space is a set of mathematical objects which collectively behave like a set of vectors.

#### Possibly confusing terminology

- Elements of a vector space may not be vectors in  $\mathbb{R}^n$
- Some textbooks (like ours) use 'vector' to refer to any element of a vector space.

## Axioms for vector space

• u + v = v + u for all u, v in V.

(addition is commutative)

- (u+v)+w=u+(v+w) for all u,v,w in V. (addition is associative)
- There is an element 0 in V, such that for all v in V, (additive identity, called "O", v + 0 = 0 + v = vexists)
- For each v in V, there exists -v in V with v + (-v) = (-v) + v = 0 (additive to verse, denoted by "-") exists)

#### Axioms (essential properties) of scalar multiplication

- distributivity • r(u+v) = ru + rv for all u, v in V and any r in  $\mathbb{R}$ .
- (r+s)v = rv + sv for all v in V and any r,s in  $\mathbb{R}$ .
- r(sv) = (rs)v for all v in V and any r, s in  $\mathbb{R}$ . (multiplication is associative)
- There is an element 1 such that 1v=v for all v in V. (multiplicative identity, called "1", exists )

An axiom is a fact that can't be reduced to a simpler property.

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## Two examples of vector spaces: $\mathbb{R}^n$ and $\mathbb{P}$

The set of vectors of height *n* is a vector space!

#### Fact (The motivating examples of vector spaces)

For each positive integer n, the set  $\mathbb{R}^n$  is a vector space.

#### Fact (Our first non-vector vector space)

The set of polynomials in x is a vector space, denoted  $\mathbb{P}$ .

Useful fact: Two polynomials are equal if and only if they have the coefficients when written in standard form:  $a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$ .

**Exercise:** Determine whether  $(x-4)^3$  is a scalar multiple of  $x^2+x+1$ .

Is there a scalar c in IR such that 
$$(x-4)^3 = c(x^2+x+1)$$
?  
First, put the LHS in Standard form:  $(x-4)(x^2-8x+16) = c(x^2+x+1)$   
 $x^3-12x^2+(32+16)x+64=c(x^2+x+1)$   
Since  $x^2+x+1$  has no  $x^3$  term this is impossible

Since x2+x+1 has no x3 term, this is impossible.

: (x-4)3 is not a scalar multiple of x2+x+1.

#### **Exercise**

▶ Write  $x^2$  as a linear combination of 1, 1 + x, and  $1 + 2x + x^2$ .

(Note: Numbers like 0, 1, and 7 count as constant polynomials!)

We want to find a,b, C in R such that 
$$X^2 = a.1 + b(1+x) + c(1+2x+x^2)$$
.

Put the RHS into standard form, so that just numbers we're trying it's easy to compare the two sides.

 $X^2 = a.1 + b(1+x) + c(1+2x+x^2)$ .

The letters a,b,c are just numbers we're trying to find.

 $X^2 = a.1 + b(1+x) + c(1+2x+x^2)$ .

Think of 1=x<sup>0</sup>

We collect all terms with  $x^2$ , all terms with  $x^2$ , and all constant terms.

 $X^2 = a.1 + b(1+x) + c(1+2x+x^2)$ .

We collect all terms with  $x^2$ , all terms with  $x^2$ , and all constant terms.

The only way the LHS equals RHS is if all coefficients match.

$$1 \cdot x^{2} + 0 \times + 0.1 = C \quad x^{2} + (b+2c) \times + (a+b+c).1$$
This tells us  $1 = C$ 

$$0 = b+2C$$

$$0 = a+b+C$$

$$0 = a+b+C$$

$$(a system of linear equations!)
$$x^{2} = 1 \cdot (1) + (2)(1+x) + (1)(1+2x+x^{2})$$

$$1 - 2(1+x) + 1+2x+x^{2} \stackrel{?}{=} x^{2}$$$$

#### Definition: The degree of a polynomial

The **degree** of a non-zero polynomial in x is the largest power of x with non-zero coefficient.

We define  $deg(0) := -\infty$ , mostly to avoid an extra case.

#### Fact (Polynomials of degree at most n)

For each positive integer n, the set of polynomials in x of degree at most n is a vector space, denoted  $\mathbb{P}_n$ .

#### **Examples:**

- $ightharpoonup \mathbb{P}_1$  consists of polynomials ax + b, for a, b in  $\mathbb{R}$ .
- ► The three polynomials  $(x-1)^3$ ,  $x^2+3x$ , and 2 are in  $\mathbb{P}_3$ , but the polynomials  $x^4$  and  $x^8-2x^3$  are not.
- $holdsymbol{\mathbb{P}}_0$  is just the constant polynomials like 0, 1, and 7, which are the same as numbers, so  $\mathbb{P}_0 = \mathbb{R}$ .

A non-example: Consider the set of polynomials of degree exactly 3.

Consider 
$$S := \{ \text{polynomials of degree exactly } 3 \}$$
.  
Then  $X^3 + X$  and  $-X^3$  are in  $S$ ,  
but their sum is not.  
So  $S$  is not closed under addition.

By a sequence, we mean an infinite list of real numbers.

#### Examples of sequences

```
0, 1, 1, 2, 3, 5, 8, 13, 21, ...
                                             (the Fibonacci sequence)
2, 3, 5, 9, 11, 13, 17, ...
                                                       (prime numbers)
1, 3, 9, 27, 81, 243, ...
                                                          (powers of 3)
7, 12, -5, \pi, 3.5, 7, \dots
                                        (Just some random numbers)
```

#### Fact (The set of sequences is a vector space)

The set of sequences is a vector space, denote S. Addition and scalar multiplication are defined term-wise.

# Fact (Sets of matrices of fixed size are vector spaces)

For positive integers m and n, the set of  $m \times n$ -matrices is a vector space, denoted  $\mathbb{R}^{m \times n}$ 

Addition and scalar multiplication are the matrix versions.

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Example: Let's say we know  $\mathbb{P}$  is a vector space, but not  $\mathbb{P}_3$ .

- ▶ To add two polynomials in  $\mathbb{P}_3$ , add them as polynomials in  $\mathbb{P}$ , and observe the result is still in  $\mathbb{P}_3$ .
- $\triangleright$  Scalar multiplication also does not leave  $\mathbb{P}_3$ .

Since the axioms hold in  $\mathbb{P}$ , they automatically hold in  $\mathbb{P}_3$ . So  $\mathbb{P}_3$  is a vector space.

## Definition: Subspace of a vector space

Let V be a vector space. A subspace of V is a non-empty subset W of Vwhich is... a. Show the zero element is in W

closed under addition; that is,

for all v, w in W, the sum v + w is in W, and

closed under scalar multiplication; that is,

for all v in W and c in  $\mathbb{R}$ , the product cv is in W.

#### Fact (Subspaces are vector spaces)

A subspace of a vector space is also a vector space.

#### **Exercise**

Let S denote the set of polynomials in  $\mathbb{P}_2$  such that f(5) = 0. That is,

$$S = \{ f(x) \text{ in } \mathbb{P}_2 \mid f(5) = 0 \}.$$

Show whether S is a subspace or not a subspace of  $\mathbb{P}_2$ .

SAMPLE STUDENT ANSWER

a. The polynomial x-5 is in  $H_2$  and plugging in 5 into x-5 gives 0. degree is  $1 \le 2$ 

So X-5 is in S. This shows S is nonempty.

b. Let f and g be in S. That is, f and g are polynomials with degree 2 or smaller, and f(5)=0

g(s)=0. So f+g is a polynomial with degree 2 or smaller, and (f+g)(s)=f(s)+g(s)=0

Therefore f + g is in S. So S is closed under addition.

C. Let c be in R and let f be in S. That is, f is a polynomial in  $\times$  with degree 2 or smaller, and f(s) = 0.

Then cf is also in  $R_2$  and (cf)(s) = c.f(s) = c.o = o

So of is in S. Therefore S is closed under scalar multiplication.

Thus, S is a subspace of P2.

— the end—

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## Exercise

Let T denote the set of polynomials in  $\mathbb{P}_2$  such that f(5) = 1. That is,

$$T = \{ f(x) \text{ in } \mathbb{P}_2 \mid f(5) = 1 \}.$$

Show whether T is a subspace or not a subspace of  $\mathbb{P}_2$ .

#### SAMPLE STUDENT ANSWER

Let f(x) := x-4, which is in T. Then (f+f)(x) = x-4+x-4= 2x-8

$$50 (f+f)(5) = 2(5)-8$$
  
= 2

Since (f+f)(5) ≠1, f+f is not in T. So T is not closed under addition.

Therefore T is not a subspace of P2.

- the end -

#### ANOTHER SAMPLE STUDENT ANSWER

Let f(x):= X-4, which is in T.

Then (4f) (x)= 4(x-4) = 4x-16

So (4f)(5) = 20-16

Since (4f)(5) #1,

4f is not in T.

So T is not closed under scalar multiplication. Therefore T is not a subspace of PZ.

- the end -

## III. A subspace spanned by a set

## Definition: Span $\{v_1, v_2, ..., v_p\}$

The span of a set of objects is the set of their linear combinations.

Example:

$$\operatorname{Span}\left\{\begin{bmatrix}1\\1\\0\end{bmatrix},\begin{bmatrix}-10\\0\\-4\end{bmatrix}\right\} := \left\{t\begin{bmatrix}1\\1\\0\end{bmatrix} + s\begin{bmatrix}-10\\0\\-4\end{bmatrix} \text{ for all } t,s \text{ in } \mathbb{R}\right\}$$

$$\operatorname{Span}\left\{\begin{bmatrix}1\\4\\7\end{bmatrix},\begin{bmatrix}2\\5\\8\end{bmatrix},\begin{bmatrix}3\\6\\0\end{bmatrix}\right\} := \left\{r\begin{bmatrix}1\\4\\7\end{bmatrix} + s\begin{bmatrix}2\\5\\8\end{bmatrix} + t\begin{bmatrix}3\\6\\0\end{bmatrix} \text{ for all } r,s,t \text{ in } \mathbb{R}\right\}$$

## Theorem: Spans are subspaces

The span of a set of objects in a vector space V is a subspace of V.

▶ Span $\{v_1, v_2, ..., v_p\}$  is called **the subspace** spanned by  $\{v_1, v_2, ..., v_p\}$ .

#### Definition: Spanning sets

A spanning set (or generating set) of H is a set of objects whose span is H.

▶ If  $H = \text{Span}\{v_1, v_2, ..., v_p\}$ , then  $\{v_1, v_2, ..., v_p\}$  is a **spanning set** for HSlide 11/12

#### Exercise

Let W be the subset of  $\mathbb{R}^3$  consisting of vectors whose second entry is the average of the other two. Show that W is a subspace of  $\mathbb{R}^3$ .

Sol: W is the Set of all vectors of the form 
$$\begin{bmatrix} a \\ \frac{1}{2}a + \frac{1}{2}b \end{bmatrix} = a \begin{bmatrix} 1 \\ \frac{1}{2} \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ \frac{1}{2} \\ 1 \end{bmatrix}$$
 where  $a, b$  are real numbers.

This implies that  $W = Span \left\{ \begin{bmatrix} 1 \\ \frac{1}{2} \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{1}{2} \\ 1 \end{bmatrix} \right\}$ ,

So  $W$  is a subspace of  $\mathbb{R}^3$ .